

Introduction to Electromagnetic Theory

Module 1: Electrostatics in vacuum (8 lectures)

Calculation of electric field and electrostatic potential for a charge distribution; Divergence and curl of electrostatic field; Laplace's and Poisson's equations for electrostatic potential and uniqueness of their solution and connection with steady state diffusion and thermal conduction; Practical examples like Faraday's cage and coffee-ring effect; Boundary conditions of electric field and electrostatic potential; method of images; energy of a charge distribution and its expression in terms of electric field.

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Module 2: Electrostatics in a linear dielectric medium (4 lectures)

Electrostatic field and potential of a dipole. Bound charges due to electric polarization; Electric displacement; boundary conditions on displacement; Solving simple electrostatics problems in presence of dielectrics – Point charge at the centre of a dielectric sphere, charge in front of a dielectric slab, dielectric slab and dielectric sphere in uniform electric field.

Module 3: Magnetostatics (6 lectures)

Biot-Savart law, Divergence and curl of static magnetic field; vector potential and calculating it for a given magnetic field using Stokes' theorem; the equation for the vector potential and its solution for given current densities.

Module 4: Magnetostatics in a linear magnetic medium (3 lectures)

Magnetization and associated bound currents; auxiliary magnetic field; Boundary conditions on \mathbf{H} and \mathbf{B} . Solving for magnetic field due to simple magnets like a bar magnet; magnetic susceptibility and ferromagnetic, paramagnetic and diamagnetic materials; Qualitative discussion of magnetic field in presence of magnetic materials.

Module 5: Faraday's law (4 lectures)

Faraday's law in terms of EMF produced by changing magnetic flux; equivalence of Faraday's law and motional EMF; Lenz's law; Electromagnetic braking and its applications; Differential form of Faraday's law expressing curl of electric field in terms of time-derivative of magnetic field and calculating electric field due to changing magnetic fields in quasi-static approximation; energy stored in a magnetic field.

Module 6: Displacement current, Magnetic field due to time-dependent electric field and Maxwell's equations (5 lectures)

Continuity equation for current densities; Modifying equation for the curl of magnetic field to satisfy continuity equation; displacement current and magnetic field arising from time-dependent electric field; calculating magnetic field due to changing electric fields in quasistatic approximation. Maxwell's equation in vacuum and non-conducting medium; Energy in an electromagnetic field; Flow of energy and Poynting vector with examples. Qualitative discussion of momentum in electromagnetic fields.

Module 7: Electromagnetic waves (8 lectures)

The wave equation; Plane electromagnetic waves in vacuum, their transverse nature and polarization; relation between electric and magnetic fields of an electromagnetic wave; energy carried by electromagnetic waves and examples. Momentum carried by electromagnetic waves and resultant pressure. Reflection and transmission of electromagnetic waves from a non-conducting medium-vacuum interface for normal incidence.

Introduction to Mechanics

Module 1: (8 lectures)

Transformation of scalars and vectors under Rotation transformation; Forces in Nature; Newton's laws and its completeness in describing particle motion; Form invariance of Newton's Second Law; Solving Newton's equations of motion in polar coordinates; Problems including constraints and friction; Extension to cylindrical and spherical coordinates

Module 2: (7 lectures)

Potential energy function; $F = -\text{Grad } V$, equipotential surfaces and meaning of gradient; Conservative and non-conservative forces, curl of a force field; Central forces; Conservation of Angular Momentum; Energy equation and energy diagrams; Elliptical, parabolic and hyperbolic orbits; Kepler problem; Application: Satellite manoeuvres;

Module 3: (5 lectures)

Non-inertial frames of reference; Rotating coordinate system: Five-term acceleration formula.
Centripetal and Coriolis accelerations; Applications: Weather systems, Foucault pendulum;

Module 4: (6 lectures)

Harmonic oscillator; Damped harmonic motion – over-damped, critically damped and lightly-damped oscillators; Forced oscillations and resonance.

Module 5: (5 lectures)

Definition and motion of a rigid body in the plane; Rotation in the plane; Kinematics in a coordinate system rotating and translating in the plane; Angular momentum about a point of a rigid body in planar motion; Euler's laws of motion, their independence from Newton's laws, and their necessity in describing rigid body motion; Examples.

Module 6: (7 lectures)

Introduction to three-dimensional rigid body motion — only need to highlight the distinction from two-dimensional motion in terms of (a) Angular velocity vector, and its rate of change and (b) Moment of inertia tensor; Three-dimensional motion of a rigid body wherein all points move in a coplanar manner: e.g. Rod executing conical motion with center of mass fixed — only need to show that this motion looks two-dimensional but is three-dimensional, and twodimensional formulation fails.